# Digital universal partical concentration sensor

PMS9003M series data manual						
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#### **Main characteristics**

- Zero false alarm rate
- Real-time response
- Correct data



- Minimum distinguishable particle diameter :0.3 micrometer
- High anti-interference performance because of the patent structure of six sides shielding
- Optional direction of air inlet and outlet in order to adapt the different design
- Smallest

#### Overview

PMS9003M is a kind of digital and universal particle concentration sensor,which can be used to obtain the number of suspended particles in the air,i.e.the concentration of particles,and output them in the form of digital interface. This sensor can be inserted into variable instruments related to the concentration of suspended particles in the air or other environmental improvement equipments to provide correct concentration data in time.

### Working principle

Laser scattering principle is used for such sensor, i.e. produce scattering by using laser to radiate suspending particles in the air, then collect scattering light in a certain degree, and finally obtain the curve of scattering light change with time. In the end, equivalent particle diameter and the number of particles with different diameter per unit volume can be calculated by microprocessor based on MIE theory. Please find the functional diagram of each part of sensor from Figure 1 as follows.

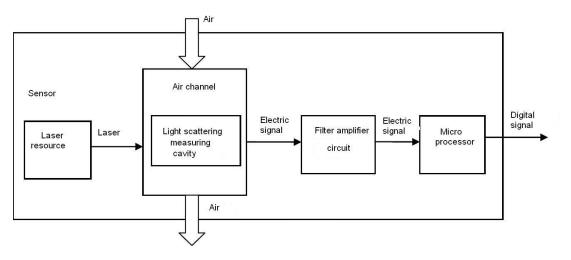


Figure 1 Functional block diagram of sensor

## **Technical Index**

Parameter	Index	unit
Particle Range of measurement	0.3~1.0; 1.0~2.5; 2.5~10	Micrometer $(\mu m)$
Particle Counting Efficiency	50%@0.3 μ m 98%@>=0.5 μ m	
Particle Effective Range (PM2.5	0~500	μ g/m³
standard )		
Particle Maximum Range	≥1000	μg/m³
(PM2.5 standard) *		
Particle Resolution	1	μg/m³
Particle Maximum Consistency	$\pm$ 10%@100~500 $\mu$ g/m <sup>3</sup>	
Error (PM2.5 standard data)*	$\pm$ 10 $\mu$ g/m³ @0~100 $\mu$ g/m³	

Particle Standard Volume	0.1	Litre (L)
Single Response Time	<1	Second (s)
Total Response Time	≤10	Second (s)
DC Power Supply	Typ:5.0 Min:4.5 Max: 5.5	Volt (V)
Active Current	≤100	Milliampere (mA)
Standby Current	≤1	Milliampere (mA)
Interface Level	L <0.8 @3.3 H >2.7@3.3	Volt (V)
Working Temperature Range	-10~+60	°C
Working Humidity Range	0~95%	
Storage Temperature Range	-40~+80	°C
MTTF	≥15000	Hour (h)
Physical Size	<b>48</b> ×40×12	Millimeter (mm)

Note 1: Maximum range means that the highest output value of the PM2.5 standard data is not less than 1000.

Note 2:"PM2.5 standard data" is the "data2" in the appendix.20°C, 50%.

### **Output result**

Mainly output as the quality and number of each particles with different size per unit volume, the unit volume of particle number is 0.1L and the unit of mass concentration is  $\mu$ g/m<sup>3</sup>.

There are two options for digital output: passive and active. Default mode is active after power up. In this mode sensor would send serial data to the host automatically. The active mode is divided into two sub-modes:stable mode and fast mode. If the concentration change is small the sensor would run at stable mode with the real interval of 2s.And if the change is big the sensor would be changed to fast mode automatically with the interval of 200~800ms, the higher of the concentration, the shorter of the interval.

## **Pin Definition**

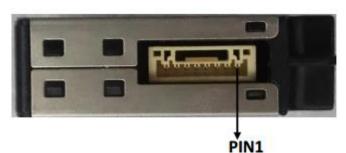


Figure 2 Connector Definition

Pin number	Pin name	Description
PIN1	VCC	Positive power 5V
PIN2	GND	Negative power
PIN3	SET	Set pin/TTL level @3.3V, high level or suspending
		is normal working status, while low level is
		sleeping mode.
PIN4	RXD	Serial port receiving pin/TTL level@3.3V
PIN5	TXD	Serial port sending pin/TTL level@3.3V
PIN6	RESET	Module reset signal/TTL level@3.3V, low reset
PIN7	NC	
PIN8	NC	

# **Typical Circuit**

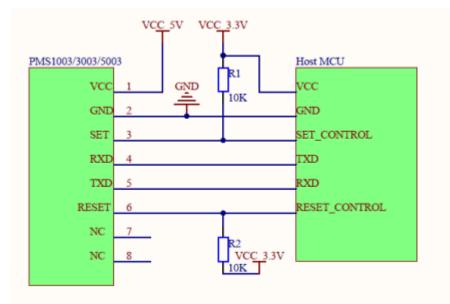


Figure 3 Typical Circuit

## **Circuit Attentions**

- DC 5V power supply is needed because the FAN should be driven by 5V. But the high level of data pin is 3.3V. Level conversion unit should be used if the power of host MCU is 5V.
- 2) The SET and RESET pins are pulled up inside so they should not be connected if without usage.
- 3) PIN7 and PIN8 should not be connected.
- 4) Stable data should be got at least 30 seconds after the sensor wakeup from the sleep mode because of the fan's performance.

### **Typical Output Characteristic**

Definition of axis Y: PM2.5 concentration, unit:  $\mu$ g/m<sup>3</sup> Definition of axis X: number of samples, unit: time

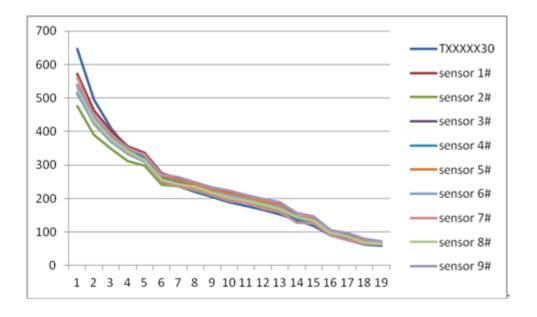


Figure 4-1 Consistency at 20  $^\circ\!\mathrm{C}$ 

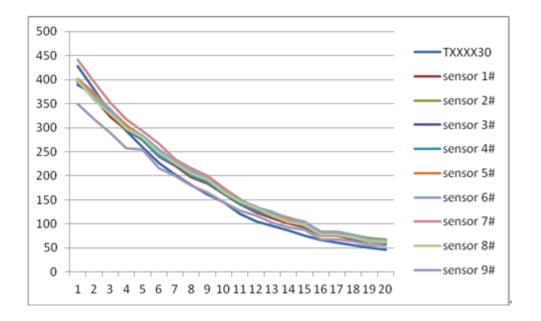


Figure 4-2 Consistency at 43°C

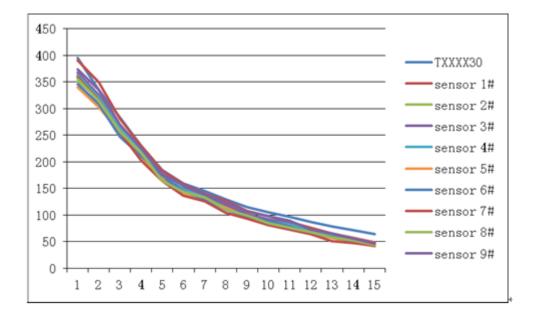


Figure 4-3 Consistency at -5°C

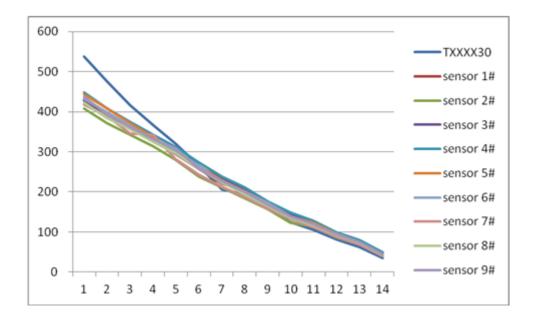


Figure 4-4 Consistency after 30 days running

Relationship of Temperature and Consistency

Definition of axis Y: Maximum Error Modulus(%) Definition of axis X: Temperature(°C)

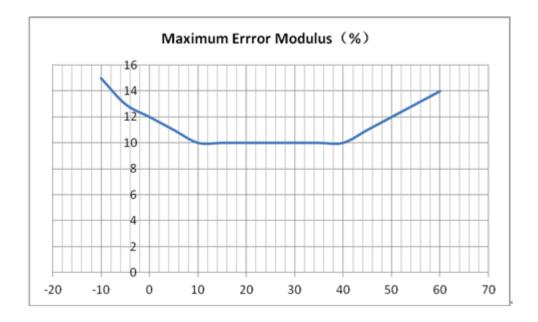


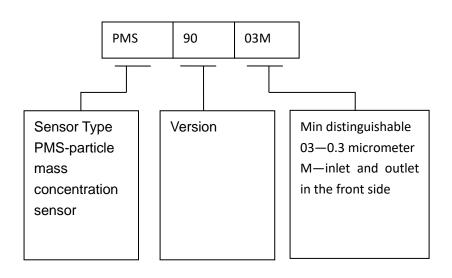
Figure 5 Consistency Vs Temperature

# **Endurance Characteristics**

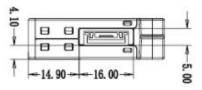
No	Item	Test Method	Characteristics	n C
1	Long Running	<ol> <li>10 m<sup>2</sup> closed Lab, 20~25°C, humidity 30%~70%, particle generator and air cleaner</li> <li>DC 5V power supply</li> <li>Check consistency after 720</li> </ol>	10 samples during $0^{500} \mu \text{ g/m}^3$ $0^{100} \mu \text{ g/m}^3$ Maximum Error $\leq$	n=30 C=0
		hours' running	$\pm$ 15 $\mu$ g/m <sup>3</sup>	
2	High Temperature Operation	<ol> <li>10 m<sup>2</sup> constant temperature Lab</li> <li>43 °C , humidity 70%,</li> <li>particle generator and air cleaner</li> <li>DC 5V power supply</li> <li>Check consistency</li> </ol>	$100^{\sim}500 \ \mu \ g/m^3$ Maximum Error $\leq \pm 15\%$	n=10 C=0
3	Cold Operation	<ol> <li>Check consistency</li> <li>10 m<sup>2</sup> constant temperature Lab</li> <li>-5°C, humidity 30%,</li> <li>particle generator and air cleaner</li> <li>DC 5V power supply</li> <li>Check consistency</li> </ol>	FAN does not screeched	n=10 C=0
4	Vibration	<ol> <li>10 m<sup>2</sup> closed Lab, 20°C, humidity 50%, particle generator and air cleaner</li> <li>DC 5V power supply and check consistency</li> <li>Frequency: 50Hz.</li> <li>acceleration: 9.8/S<sup>2</sup>.</li> <li>Direction: X Y Z</li> <li>Vibration Amplitude: ±2mm.</li> </ol>		n=5 C=0
5	High Temperature and Humidity Storage	<ol> <li>Time: X、Y、Z-way, Per 1 hour</li> <li>Constant temperature cabinet</li> <li>70°C, humidity 90%~95,</li> <li>Check consistency after 500 hours' storage</li> </ol>	10 samples during 0~500 μ g/m <sup>3</sup> 0~100 μ g/m <sup>3</sup>	n=10 C=0
6	Cold Storage	<ol> <li>Constant temperature cabinet</li> <li>-30°C, humidity 90%~95,</li> <li>Check consistency after 500 hours' storage</li> </ol>	Maximum Error $\leq \pm 10 \ \mu \text{ g/m}^3$ 100~500 $\ \mu \text{ g/m}^3$ Maximum Error $\leq$	n=10 C=0

				±10%	6		
7	Variation of	4.	10 $\text{m}^2$ closed Lab, , 20 $^\circ\!\mathrm{C}$ ,				n=5
	Power Supply		humidity 50%, particle				C=0
			generator and air cleaner	FAN	does	not	
				screed	ched		
		5.	Power varies as the cycles of 4.5V				
			to 5.5V ,then 5.5V to 4.5V with the				
			pace of 0.1V/min for 2 hours.				
		6.	Check consistency during				
			Variation				
8	Power On-Off	1.	10 ${\tt M}^{\scriptscriptstyle 2}$ closed Lab, , 20 $^\circ\!{\rm C}$ ,				n=10
	Cycle		humidity 50%, particle				C=0
			generator and air cleaner				
		2.	DC 5V power supply, keep On-				
			Off frequency 0.5Hz for 72 hours				
			and check consistency				
9	Sleep Set On-	1.	10 ${\tt M}^{\scriptscriptstyle 2}$ closed Lab, , 20 $^\circ\!{\rm C}$ ,				n=10
	Off		humidity 50%, particle				C=0
	Cycle		generator and air cleaner				
		2.	DC 5V power supply, keep Sleep				
			Set Pin High-Low frequency 0.5Hz				
			for 72 hours and check				
			consistency				
10	Laser On-Off	1.	10 ${\rm m}^{\scriptscriptstyle 2}$ closed Lab, , $$ 20 $^{\circ}\!{\rm C}$ ,				n=10
	Cycle		humidity 50%, particle				C=0
			generator and air cleaner				
		2.	keep laser On-Off frequency				
			50Hz for 240 hours and check				
			consistency				
11	Salt Spray	5%	industrial salt water, hydrolysis	No	rust	and	n=1
		spi	ray 100 hours, clean with purified	discol	loration	of	C=0
		wa	ter and store for 48 hours	metal	parts		

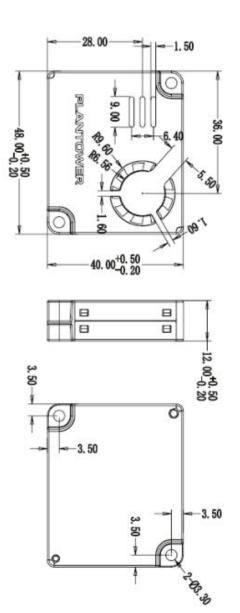
## **Part Number Definition**



# Physical Size(mm)







## **Installation Attentions**

- 1) Metal shell is connected to the GND so be careful not to let it shorted with the other parts of circuit except GND.
- 2) The best way of install is making the plane of inlet and outlet closely to the plane of the host. Or some shield should be placed between inlet and outlet in order to prevent the air flow from inner loop.
- 3) The blowhole in the shell of the host should not be smaller than the inlet.
- 4) The sensor should not be installed in the air flow way of the air cleaner or should be shielded by some structure.
- 5) The sensor should be installed at least 20cm higher than the grand in order to prevent it from blocking by the flock dust.
- 6) When the sensor is used to outdoor fixed equipment, the equipment should be completed for the protection of sandstorm, rain, snow, etc.
- 7) Do not break up the sensor.

## **Other Attentions**

- 1) Only the consistency of all the PM sensors of PLANTOWER is promised and ensured. And the sensor should not be checked with any third party equipment.
- 2) The sensor is usually used in the common indoor environment. So some protection must be added if using in the conditions as followed:
  - a) The time of concentration  $\geq$  300 µ g/m<sup>3</sup> is longer than 50% of the whole year or concentration  $\geq$  500 µ g/m<sup>3</sup> is longer than 20% of the whole year.
  - b) Kitchen
  - c) Water mist condition such as bathroom or hot spring.
  - d) Outdoor

### Value Conversion

This sensor can be numerically converted to TSI8530, a special device of the US TSI. There are two methods:

- Send instructions to the sensor(Instructions are defined in appendix B),activate the curve,the atmospheric environment value in the original output data of the sensor(see appendix A,data 5)can be converted to the exactly corresponding to TSI8530.
- 2. The client obtains the standard particulate value of the sensor(see appendix A,data 2),and the value of CF=1 of TSI8530 can be obtained according to the following formula.Furthermore,by multiplying the conversion result of the formula by 0.38,the value of CF=0.38 of TSI8530 can be obtained.

$$Y = X (X=0)$$

$$Y = 1/(0.62/X - 0.0003)$$
 (X>0)

Y:Values corresponding to TSI8530(CF=1) X:Standard concentration(data 2) Calculation case

x	γ	TSI CF=1	Y*0.38	TSI
1105	3830	4020	1455	1528
1003	3143	3300	1194	1254
938	2770	2840	1053	1079
861	2380	2470	905	939
753	1911	1970	726	749
670	1599	1640	608	623
566	1257	1290	478	490
517	1112	1120	423	426
468	976	984	371	374
408	820	819	312	311
361	705	699	268	266
308	584	576	222	219
263	486	480	185	182
221	399	395	152	150
162	284	273	108	104

127	218	212	83	81
86	145	141	55	54
48	79	79	30	30
31	51	53	19	20
11	18	21	7	8

# Appendix I: transport protocol Active Mode

# Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

32 Bytes				
Start character 1	0x42	(Fixed)		
Start character2	0x4d	(Fixed)		
Frame length high 8 bits		Frame length=2x13+2(data+check bytes)		
Frame length low 8 bits				
Data 1 high 8 bits		Data1 refers to PM1.0 concentration unit µ g/m3 (CF=1, standard particle) *		
Data 1 low 8 bits		μ g/m3 (Of =1; standard particle)		
Data2 high 8 bits		Data2 refers to PM2.5 concentration unit		
Data2 low 8 bits		μ g/m3 (CF=1, standard particle)		
Data3 high 8 bits		Data3 refers to PM10 concentration unit		
Data3 low 8 bits		μ g/m3 (CF=1, standard particle)		
Data4 high 8 bits		Data4 refers to PM1.0 concentration unit		
Data4 low 8 bits		μ g/m3 (under atmospheric environment)		
Data5 high 8 bits		Data 5 refers to PM2.5 concentration unit		
Data5 low 8 bits		μ g/m3 (under atmospheric environment)		
Data6 high 8 bits		Data 6 refers to concentration unit (under		
Data6 low 8 bits		atmospheric environment) μ g/m3		
Data7 high 8 bits		Data7 indicates the number of		
Data7 low 8 bits		particles with diameter beyond 0.3 um in 0.1 L of air.		
Data8 high 8 bits		Data 8 indicates the number of		
Data8 low 8 bits		particles with diameter beyond 0.5		
	•••••	um in 0.1 L of air.		
Data9 high 8 bits		Data 9 indicates the number of particles with diameter beyond 1.0		
Data9 low 8 bits		um in 0.1 L of air.		
Data10 high 8 bits		Data10 indicates the number of particles with diameter beyond 2.5		
Data10 low 8 bits		um in 0.1 L of air.		

Data11 high 8 bits	 Data11 indicates the number of particles with diameter beyond 5.0
Data11 low 8 bits	 um in 0.1 L of air.
Data12 high 8 bits	 Data12 indicates the number of particles with diameter beyond 10 um
Data12 low 8 bits	 in 0.1 L of air.
Data13 high 8 bits	 Version
Data13 low 8 bits	 error code
Data and check high 8 bits	 Check code=Start character 1+ Start character 2++data 13
Data and check low 8 bits	 Low 8 bits

Note: CF=1 should be used in the factory environment

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### Appendix II: transport protocol Passive Mode

Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

Host Protocol

Start Byte	Start Byte	Command	Data 1	Data 2	Verify	Verify
1	2				Byte 1	Byte 2
0x42	0x4d	CMD	DATAH	DATAL	LRCH	LRCL

#### 1. Command Definition

CMD	DATAH	DATAL	Note
0xe2	Х	X	Read in passive
			mode
0xe1	X	00H-passive	Change mode
		01H-active	
0xe4	X	00H-sleep	Sleep set
		01H-wakeup	
0x52	Х	01H-primitive curve	Activate TSI
		02H-TSI CF=0.38	curve
		03H-TSI CF=1	

### 2. Answer

- a) 0xe2: 32bytes , same as appendix I
- b) 0xe1:

Start	Start	Frame	Frame	Command	Data	Verify	Verify
Byte 1	Byte 2	length1	length2			Byte 1	Byte 2
0x42	0x4d	0x00	0x04	0xe1	work	LRCH	LRCL

#### c) 0xe4:

Start	Start	Frame	Frame	Command	Data	Verify	Verify
Byte 1	Byte 2	length1	length2			Byte 1	Byte 2
0x42	0x4d	0x00	0x04	0xe4	sleep	LRCH	LRCL

#### d) 0x52:

Start	Start	Frame	Frame	Command	Data	Verify	Verify
Byte 1	Byte 2	length1	length2			Byte 1	Byte 2
0x42	0x4d	0x00	0x04	0x52	curve	LRCH	LRCL

### 3. Verify Bytes :

Add of all the bytes except verify bytes.